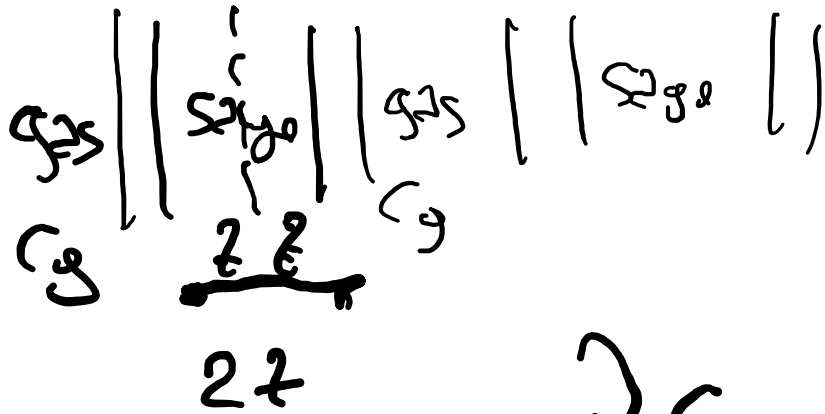


$$\frac{\partial c'}{\partial t} = D_1 \frac{\partial^2 c'}{\partial x^2}$$

$$\frac{\partial c}{\partial t} = D_2 \frac{\partial^2 c}{\partial x^2} + \underline{K'(y_0 - y) - Kcy}$$



$$\frac{\partial y}{\partial t} = D_H b \frac{\partial^2 y}{\partial x^2} + K'(y_0 - y) - Kcy$$

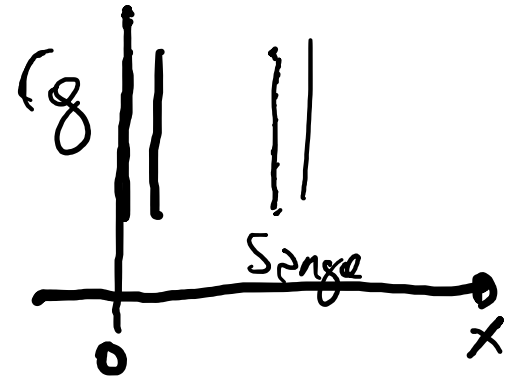
$$\frac{\partial c}{\partial t} = D_M \frac{\partial^2 c}{\partial x^2}$$

$$D_M \approx D_2$$

$$\frac{1}{D_2} = \frac{1}{D_M} + \frac{1}{\theta_{vc}}$$

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2}$$

$c(x, t)$



$$\begin{cases} \frac{\partial c}{\partial t} = A & \textcircled{1} \\ \frac{\partial^2 c}{\partial x^2} = \frac{A}{D} & \textcircled{2} \end{cases}$$

$$c(x, t) - c(x, 0) = At + B.$$

$$c(x, 0) = \phi \quad \forall x \neq 0 \quad t = 0$$

$$c(x, t) = At$$

$$c(0, 0) = C_g$$

$$c(0, 0) = C_g = B.$$

$$c(x, t) = At + C_g \quad A = \frac{c(x, t) - C_g}{t}$$

$$\frac{\partial^2 c}{\partial x^2} = \frac{A}{Dn}$$

$$\frac{\partial c}{\partial x} = \frac{A}{Dn} x + E$$

$$c(x, t) - c(0, t) = \frac{A}{2Dn} x^2 + Ex + F$$

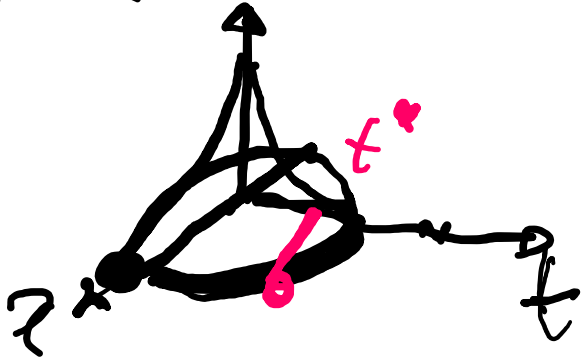
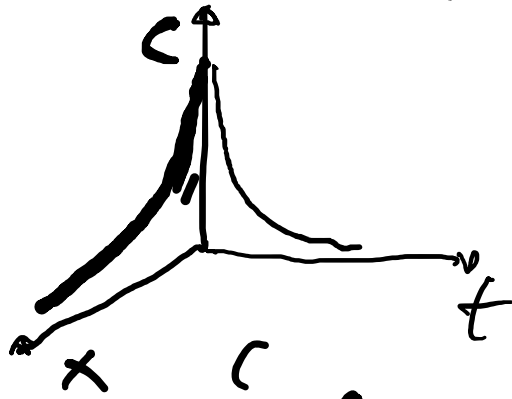
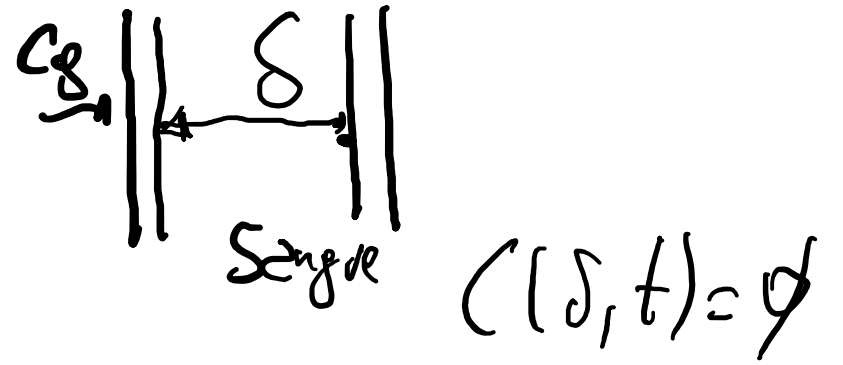
$c_0$

$$c(x, t) = c_0 + \frac{c(x, t) - c_0}{t} \frac{x^2}{2Dn} + Ex + F$$

$$c(x, t) = c_0 + c(x, t) \cdot \frac{x^2}{2Dnt} - \frac{c_0 x^2}{2Dnt} + Ex + F$$

$$c(x, t) \left[ 1 - \frac{x^2}{2Dnt} \right] = c_0 \left[ 1 - \frac{x^2}{2Dnt} \right] + Ex + F$$

$$C(x, t) = \frac{C_0 \left[ 1 - \frac{x^2}{2D\pi t} \right] + Ex + F}{\left[ 1 - \frac{x^2}{2D\pi t} \right]}$$



$$C(x, t) \approx C_0 + E \frac{x}{-x^2} - \frac{F}{-x^2}$$

$-\frac{1}{x}$

$$\frac{\partial c}{\partial t} = D_1 \frac{\partial^2 c}{\partial x^2} + R_{O_2}$$

$$R_{O_2} = \left[ \frac{\text{mol}}{\text{cm}^3 \cdot \text{sec}} \right]$$

$$\frac{\partial y}{\partial t} = D_{HB} \frac{\partial^2 y}{\partial x^2} + R_{HB}$$

$$R_{O_2} + R_{HB} = \phi$$

$$D_{HB} = \phi$$

$$\frac{\partial c}{\partial t} = \phi$$

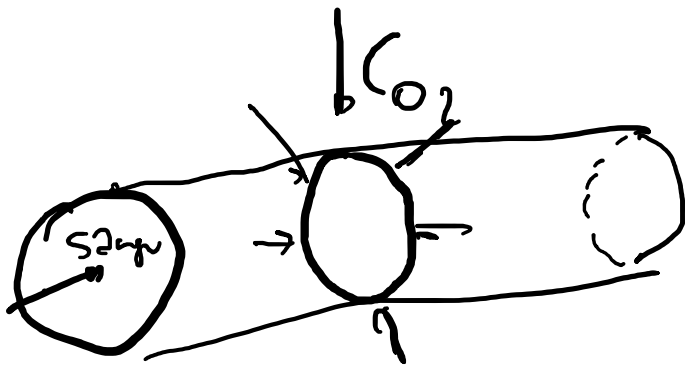
$$D_2 \frac{\partial^2 c}{\partial x^2} + \frac{\partial y}{\partial t} = -R_{O_2} - R_{HB} = -(R_{O_2} + R_{HB}) = \phi$$

$$\left\{ \begin{array}{l} D_2 \frac{\partial^2 c}{\partial x^2} = -R_{O_2} \\ \frac{\partial y}{\partial t} = R_{HB} \end{array} \right.$$

$$D_L \frac{\partial^2 c}{\partial x^2} - \frac{\partial y}{\partial t} = \phi$$

$$\frac{\partial y}{\partial t} = D_L \frac{\partial^2 c}{\partial x^2}$$

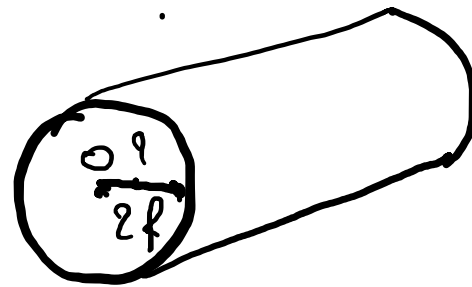
equazione del fronte di avanzamento.  
in regime reversibile.



$$J_{O_2} = -D \frac{\partial c}{\partial r}$$

$$-D \frac{\partial c}{\partial r}, 2\pi r = A$$

$$\left[ \frac{m^2}{s} \right] \cdot \left[ \frac{m \cdot di}{m^3} \right]$$



$$\left[ \frac{m \cdot di}{m \cdot s} \right]$$

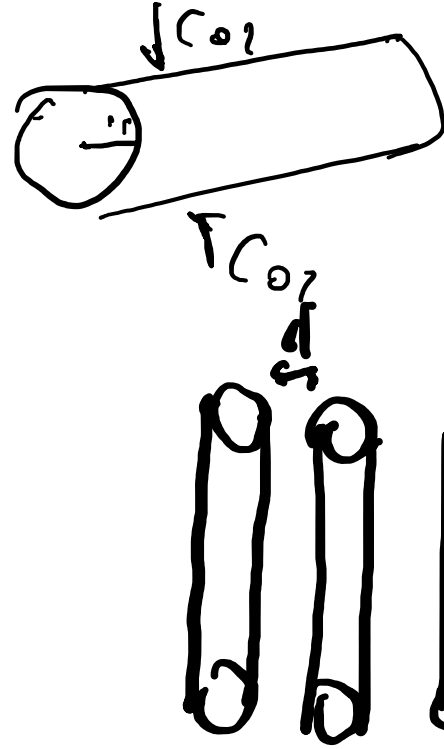
$$\int_{c(r)}^{c(2l)} \partial c = -\frac{A}{D} \int_r^{2l} \frac{\partial r}{2\pi r}$$

$$c(2l) - c(r) = -\frac{A}{2\pi D} \cdot \ln \frac{2l}{r} = \frac{A}{2\pi D} \ln \frac{r}{2l}$$

$$C(r) = C(r_f) - \frac{A}{2\pi D} \ln \frac{r}{r_f}$$

$$C(r) = C_a - \frac{A}{2\pi D} \ln \frac{r}{r_f}$$

$$C(r) = \phi$$



$$\underline{W} = \underline{K} \left( \underset{P_{Gin}}{P_G} - \underset{P_{Gout}}{P_B} \right)$$

$\Delta P_G$

$$W = \frac{250 \text{ ml}}{\text{min}} \text{ O}_2$$

$$K = \frac{700 \text{ ml}}{\text{min}} \text{ CO}_2$$