

Electronic Prototyping

Interrupt, Flow chart, Batteries, Fritzing

Lesson 7



Interrupt

Interrupts

- An interrupt, in microcontroller context, is a signal that temporarily stops what the CPU is currently working at.
- When a sketch is executed, the top most lines are run first. So logically the *setup()* function is run before the *loop()* function. The *loop()* function is an endless loop so there is no way to exit it.
- If we will now use interrupts, we add a third function named *isr()*. ISR is short for *Interrupt Service Routine*. This is where the program jumps to whenever there is an interrupt. An ISR cannot have any parameters, and they shouldn't return anything.

Interrupts

- When does the program jump to `isr()`? For the Arduino platform, there will be an interrupt when specific pins change their state. If the interrupt pin is normally high, when it becomes low, then the interrupt is triggered and the program jumps to `isr()`.

```
void setup(){  
2 }  
3  
4 void loop(){  
5 }  
6  
7 void isr(){  
8 }
```

Interrupt pins for different Arduino boards

BOARD	DIGITAL PINS USABLE FOR INTERRUPTS
Uno , Nano, Mini, other 328-based	2, 3
Uno WiFi Rev.2	all digital pins
Mega, Mega2560, MegaADK	2, 3, 18, 19, 20, 21
Micro, Leonardo, other 32u4-based	0, 1, 2, 3, 7
Zero	all digital pins, except 4
MKR Family boards	0, 1, 4, 5, 6, 7, 8, 9, A1, A2
Due	all digital pins
101	all digital pins (Only pins 2, 5, 7, 8, 10, 11, 12, 13 work with CHANGE)

Syntax: attachInterrupt()

- **attachInterrupt**(digitalPinToInterrupt(pin), ISR, mode); Arduino Uno
- **attachInterrupt**(pin, ISR, mode); Arduino Due

Syntax: attachInterrupt()

mode: defines when the interrupt should be triggered. Four constants are predefined as valid values:

- **LOW** to trigger the interrupt whenever the pin is low,
- **CHANGE** to trigger the interrupt whenever the pin changes value
- **RISING** to trigger when the pin goes from low to high,
- **FALLING** for when the pin goes from high to low.

The Due, Zero and MKR1000 boards allows also:

- **HIGH** to trigger the interrupt whenever the pin is high.

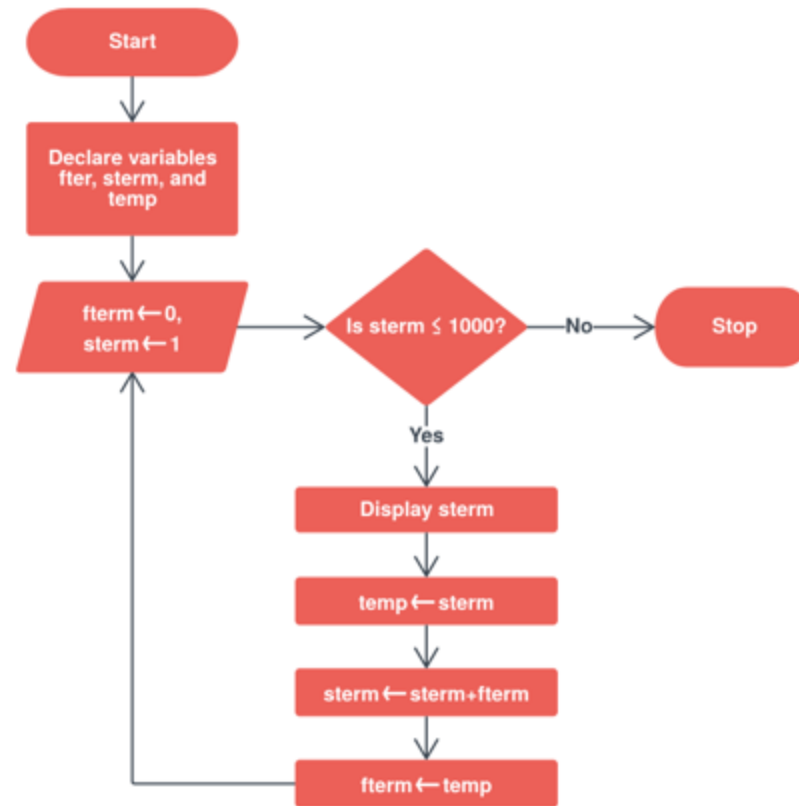
Example

```
const byte ledPin = 13;
const byte interruptPin = 2;
volatile byte state = LOW;

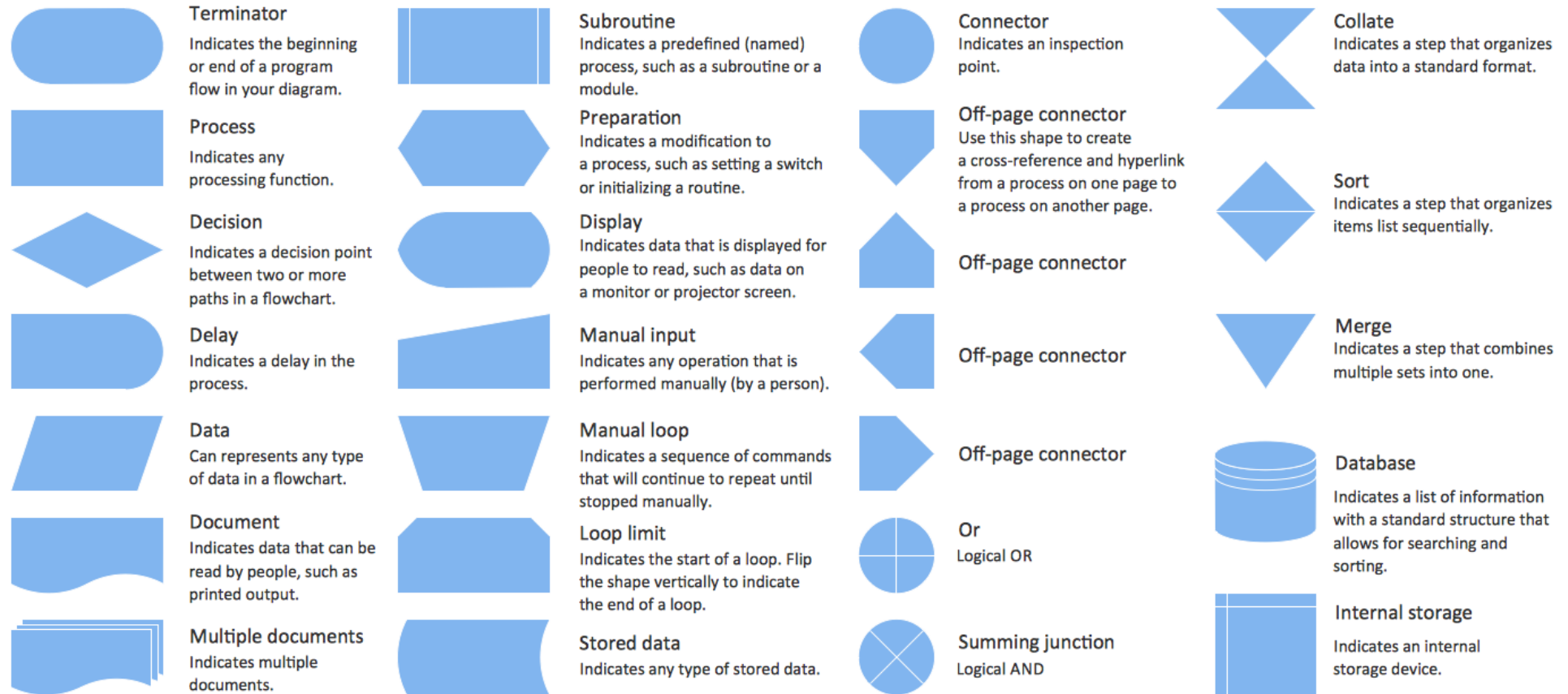
void setup() {
  pinMode(ledPin, OUTPUT);
  pinMode(interruptPin, INPUT_PULLUP);
  attachInterrupt(digitalPinToInterrupt(interruptPin), blink, CHANGE); //Arduino Uno
  attachInterrupt(2, blink, CHANGE); //Arduino Due
}
void loop() {
  digitalWrite(ledPin, state);
}
void blink() {
  state = !state;
}
```


Flow chart

Flow chart

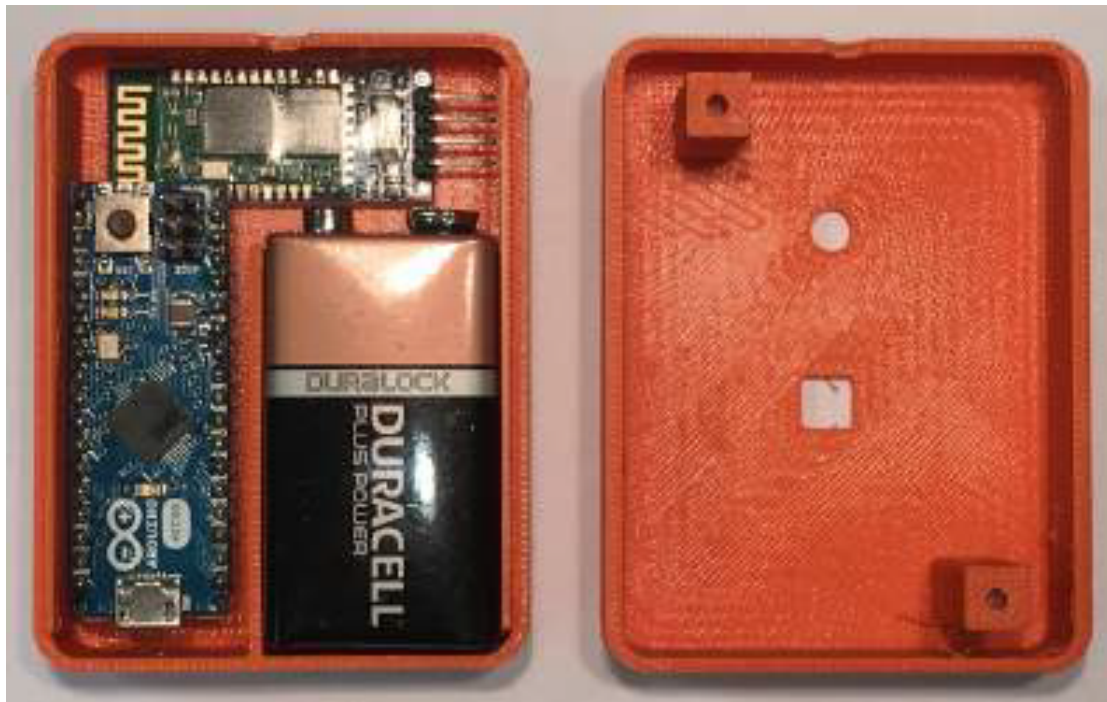


Flow chart elements



Batteries

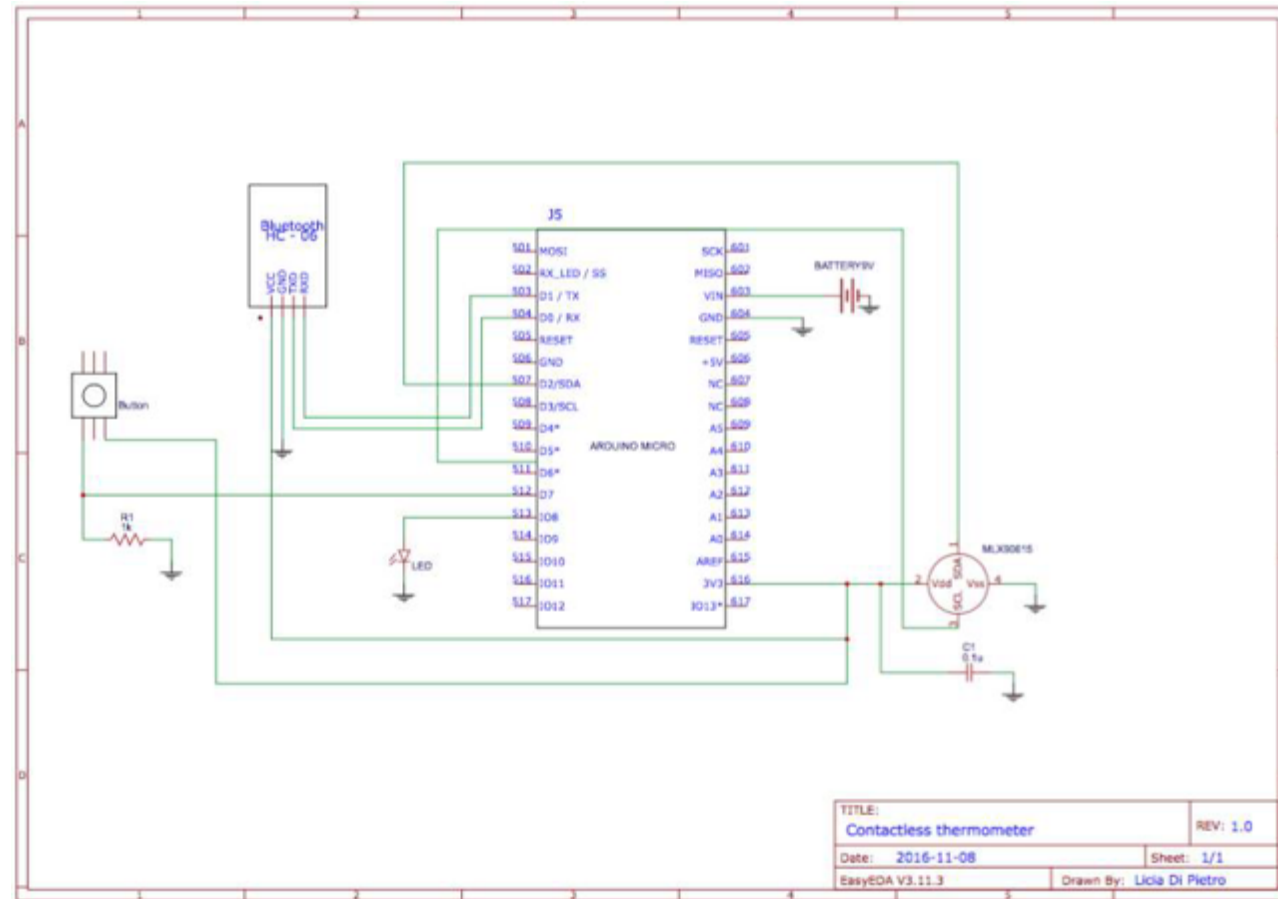
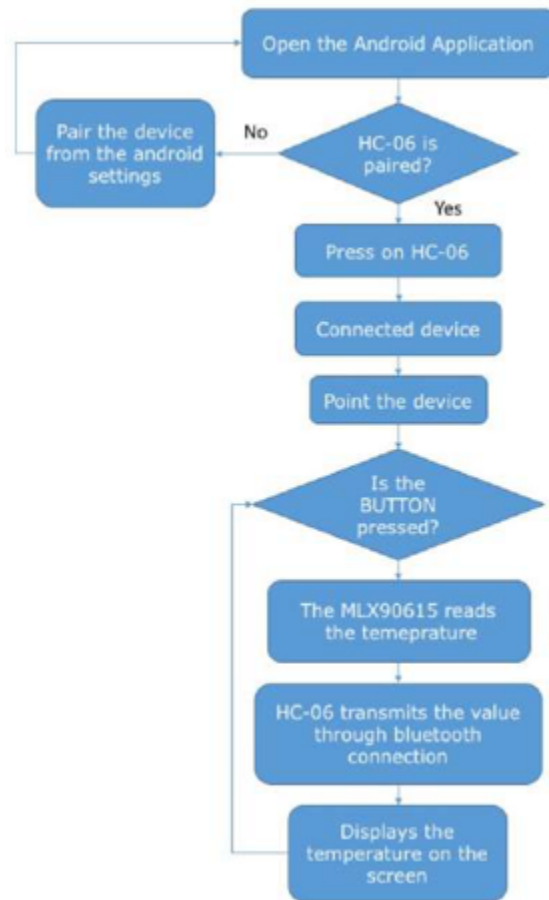
Example: contactless thermometer



MLX90615 by Melexis

Battery capacity 550 mAh @9 V

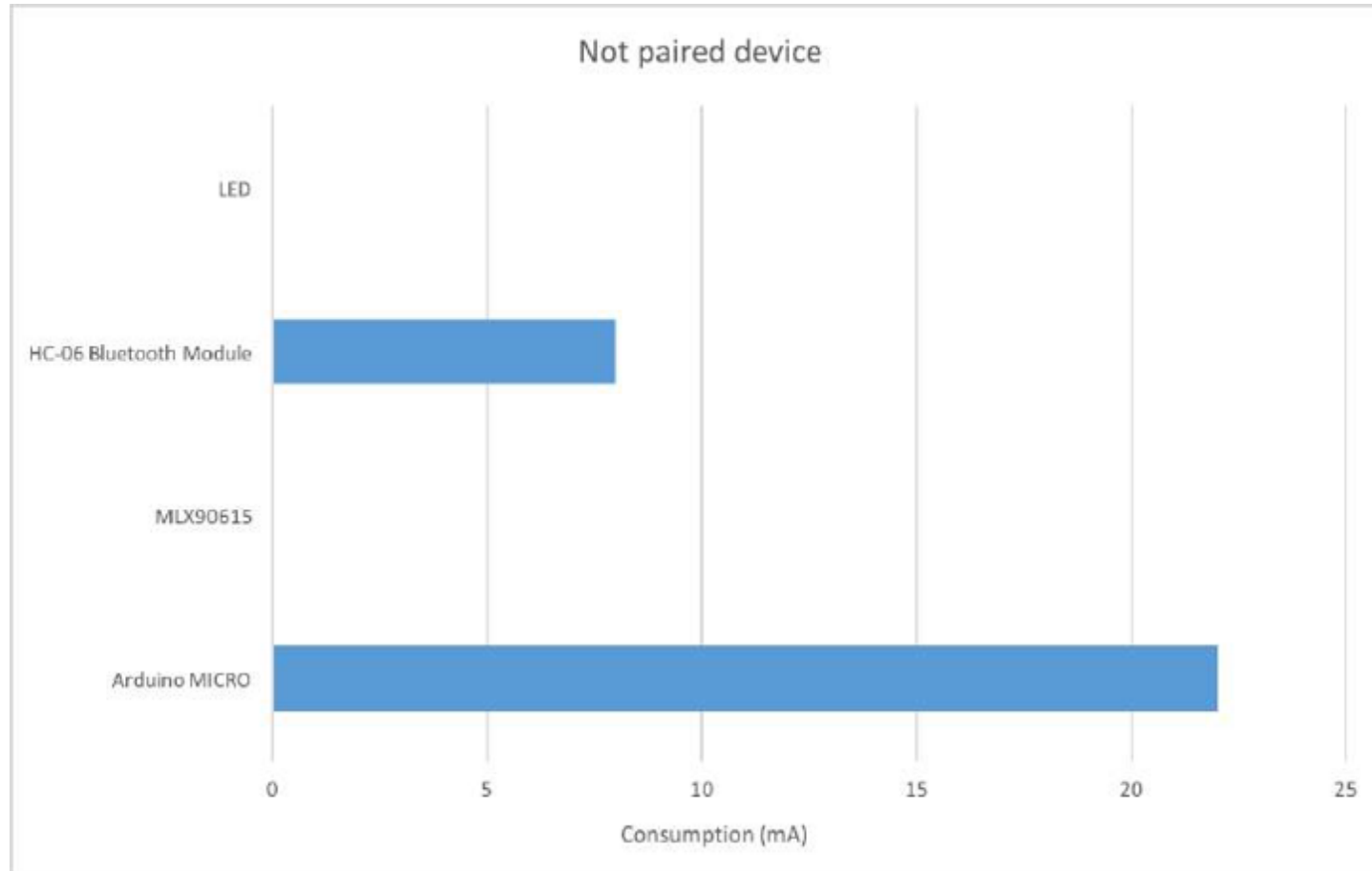
Contactless thermometer



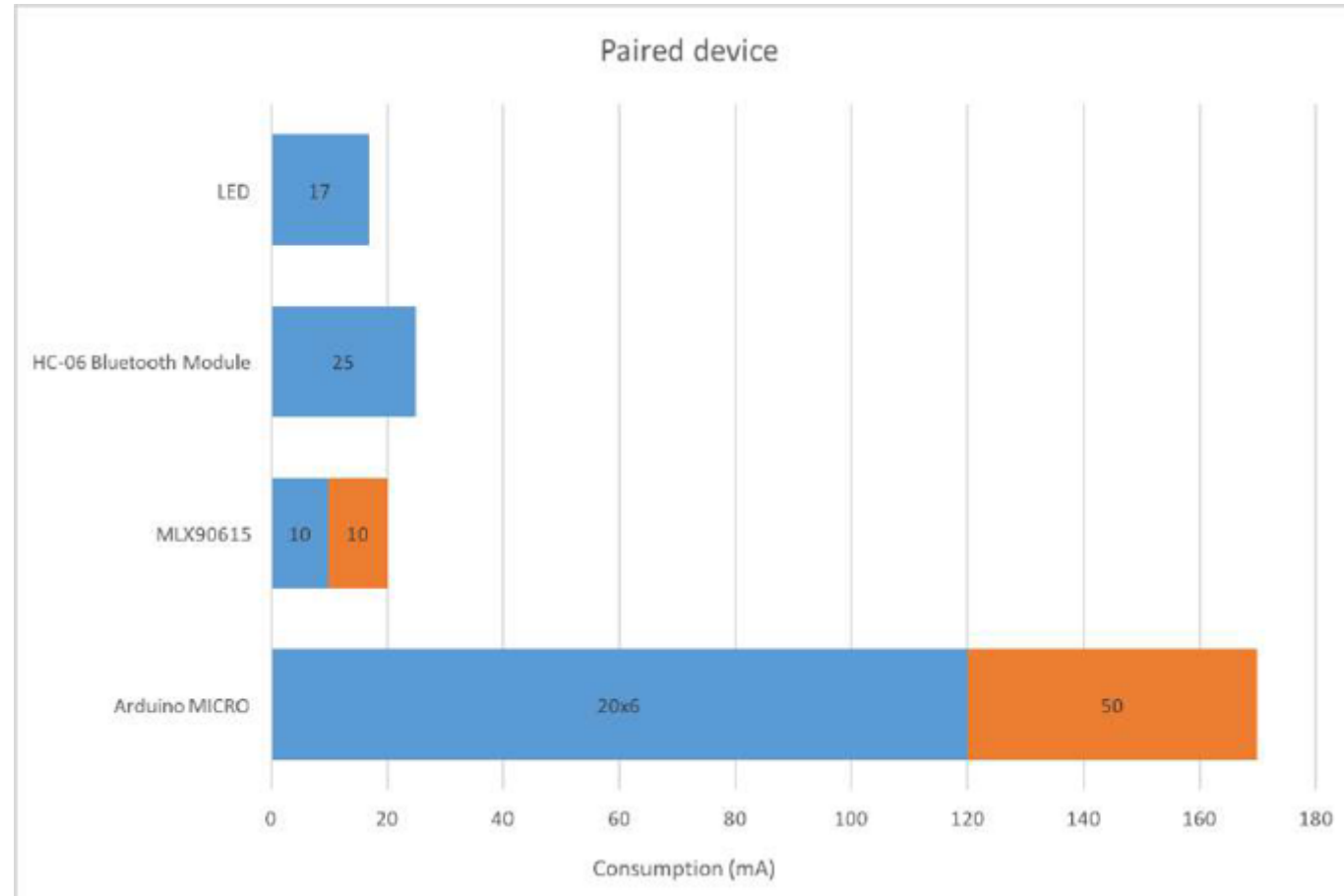
Current consumption

Arduino Micro Board	
DC Current per I/O Pin	20 mA
DC Current for 3.3V Pin	50 mA
Sleep Mode	20 mA
MLX90615 InfraRed Sensor	
DC clamp current, SDA pin	10 mA
DC clamp current, SCL pin	10 mA
HC-06 Bluetooth Module	
During the pairing	25 mA
After pairing	8 mA
LED-Basic Led 5mm	
Using current	16-18 mA

Current consumption



Current consumption



Current consumption

Using the device in continuous way the battery life is 2h 22m 12s but considering that the duration of only one read is about 6s, is possible using the thermometer for 1422 times, as calculated in Equation 3.4.

$$\frac{12s}{6s} + \frac{22 \times 60s}{6s} + \frac{2 \times 60 \times 60s}{6s} = 1422 \quad (3.4)$$

Fritzing & Tinkercad

How to simulate your prototype?



<https://fritzing.org/home/>



<https://www.tinkercad.com/>

